

# It's a Noncommutative World After All

Lara Ismert

University of Nebraska-Lincoln

**Math Club! @ University of Texas at Tyler**

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# Noncommutative Happenings in Everyday Life

**Commutative Operations:** For any real numbers  $a$  and  $b$ ,

$$a + b = b + a \text{ and } ab = ba.$$

“Addition and multiplication are commutative.”

**Noncommutative Operations:**

- Getting dressed
- Doing laundry
- Function composition

## Example

If  $f(x) = x^2$  and  $g(x) = x + 1$ , does  $f(g(x)) = g(f(x))$ ?

$$f(g(x)) = (x + 1)^2 \text{ and } g(f(x)) = x^2 + 1.$$

# Examples of Noncommutative Operations

- Getting dressed
- Doing laundry
- Function composition

## Example

If  $f(x) = x^2$  and  $g(x) = x + 1$ , does  $f(g(x)) = g(f(x))$ ?

**No:**  $(x + 1)^2 \neq x^2 + 1$ .

$\Rightarrow$   $f$  and  $g$  do not commute under *function composition*:

$$f \circ g \neq g \circ f.$$

# Composition of Function Transformations

Function *transformations* are functions on functions.

- **Translations:** Apply  $T_c$  to a function  $f$  by  $[T_c f](x) = f(x) + c$ .
- **Scaling:** Apply  $S_d$  to a function  $f$  by  $[S_d f](x) = df(x)$ .

## Example

Do  $T_c$  and  $S_d$  commute with respect to function composition? That is, for any function  $f$ , does

$$(T_c \circ S_d)f = (S_d \circ T_c)f?$$

Consider  $c = 1$  and  $d = 2$ .

<https://www.desmos.com/calculator/axkqbn7se3>

# Composition of Function Transformations

- **Multiplication:** Apply  $Q$  to  $f$  by  $[Qf](x) = xf(x)$ .
- **Differentiation:** Apply  $P$  to  $f$  by  $[Pf](x) = f'(x) \cdot i = if'(x)$ .

## Example

Do  $Q$  and  $P$  commute with respect to function composition? That is, for any function  $f$ , does

$$(Q \circ P)f = (P \circ Q)f?$$

$$(P \circ Q)f - (Q \circ P)f = if$$

The transformations  $P$  and  $Q$  are known as the “momentum” and “position” transformations. This relation is known as the

**Heisenberg Commutation Relation.**

# The Double Slit Experiment

- 1 Shoot electrons out of a (stationary) electron beam at a screen with two slits cut in it.
- 2 A second screen (behind the first) detects where the electrons land.

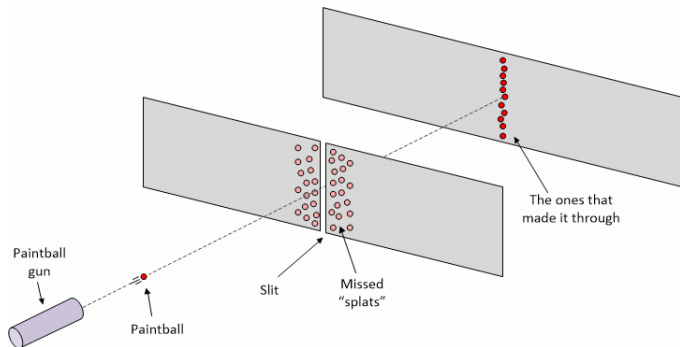


Figure: If electrons were paintballs.

# The Double Slit Experiment

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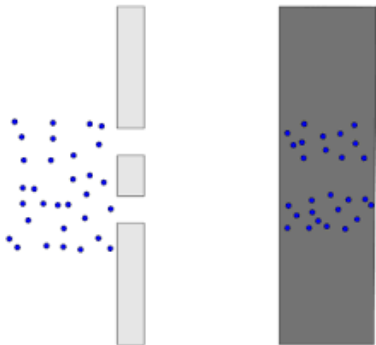


Figure: Paintballs through two slits.



# The Double Slit Experiment

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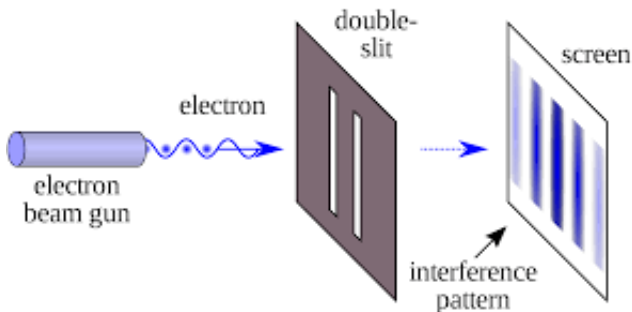


Figure: Actual Double Slit Experiment.

# The Double Slit Experiment

**Conclusions:** Electrons are not paintballs, nor do they behave like them. Instead, electrons (and other quantum particles) behave much like waves—unpredictably. But, they do behave probabilistically.

A particle's motion is represented by a function,  $\psi$ , that contains *probabilistic* information.

- 1 We call  $\psi$  the **state** of the particle.
- 2 We require  $\psi(x) \cdot \psi(x) = \psi(x)^2$  to be a *probability density function*:

$$\int_{-\infty}^{\infty} \psi(x)^2 dx = 1.$$

# Quantum States

How do we compare two states  $\psi$  and  $\phi$ ?

$$\langle \psi, \phi \rangle = \int_{-\infty}^{\infty} \psi(x) \cdot \phi(x) dx.$$

Think of the *dot product* of two **unit** vectors:

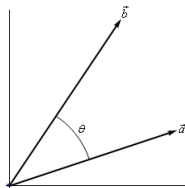


Figure:  $\mathbf{a} \cdot \mathbf{b} = \cos \theta$ .

$\Rightarrow \langle \psi, \phi \rangle$  is measuring some geometric difference between  $\psi$  and  $\phi$ .

<https://www.desmos.com/calculator/utix5squrb>

# Quantum Measurements

Why did we call  $Q$  the **position** transformation?

- If  $\psi(x)^2$  is the p.d.f. for position, the *expected value* is

$$\int_{-\infty}^{\infty} x\psi(x)^2 dx = \int_{-\infty}^{\infty} x\psi(x) \cdot \psi(x) dx = \langle Q\psi, \psi \rangle .$$

- Let  $E(Q) := \langle Q\psi, \psi \rangle$ .

Let's use this same idea for **momentum**:

$$E(P) = \langle P\psi, \psi \rangle = \int_{-\infty}^{\infty} i\psi'(x) \cdot \psi(x) dx.$$

What's the idea behind the *expected value*?

## Example

Consider a *probability mass function*  $\psi(x)^2 = p(x)$  on the positions  $x = \{0, 1, 2\}$  given by

$$p(0) = 0.5 \quad p(1) = 0.3 \quad p(2) = 0.2.$$

Note:  $\sum_{n=0}^2 p(n) = 1.$

Then the expected value of the position is

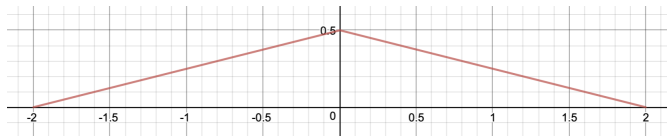
$$E(Q) = \sum_{n=0}^2 np(n) = 0p(0) + 1p(1) + 2p(2) = 0(0.5) + 1(0.3) + 2(0.2) = 0.7.$$

So an expected value is a *weighted average*.

# Expected Values

## Example

Let  $p(x) = \frac{1}{2}(1 - |\frac{1}{2}x|)$  for  $-2 \leq x \leq 2$ , and  $p(x) = 0$  otherwise.



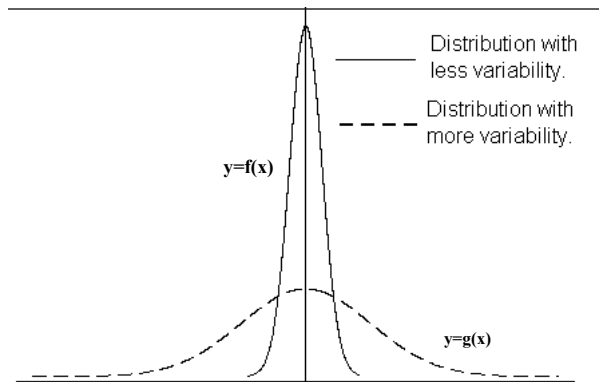
- Note:  $\int_{-\infty}^{\infty} p(x) dx = 1$ .

Where do you expect to find the particle?

$$E(Q) = \int_{-\infty}^{\infty} xp(x) dx = 0.$$

How certain are you that you'll find it near  $x = 0$ ?

# More Ideas from Probability



**Moral:** Less spread in probability relates to higher certainty.

**Goal:** Minimize the *variance*, the square of the *standard deviation*

$$\sigma^2 = E(Q^2) - E(Q)^2.$$

# Simultaneous Pursuit for Certainty

Can we simultaneously improve our certainty of  $E(Q)$  and  $E(P)$ ?

- Let  $\tau^2 = E(P^2) - E(P)^2$  be the variance for  $P$ .
- Let's try to simultaneously *minimize*  $\sigma^2$  and  $\tau^2$  by minimizing  $\sigma^2\tau^2$ .

Let's be clever!

$$\begin{aligned}\sigma^2 &= E(Q^2) - E(Q)^2 = E(Q^2) - 2E(Q)^2 + E(Q)^2 \\ &= \int_{-\infty}^{\infty} x^2\psi(x)^2 dx - 2E(Q) \int_{-\infty}^{\infty} x\psi(x)^2 dx + E(Q)^2 \int_{-\infty}^{\infty} \psi(x)^2 dx \\ &= \int_{-\infty}^{\infty} x^2\psi(x)^2 - 2E(Q)x\psi(x)^2 + E(Q)^2\psi(x)^2 dx \\ &= \int_{-\infty}^{\infty} [x^2 - 2E(Q)x + E(Q)^2] \psi(x)^2 dx = \int_{-\infty}^{\infty} [x - E(Q)]^2 \psi(x)^2 dx\end{aligned}$$



# Simultaneous Pursuit for Certainty

So

$$\sigma^2 = \int_{-\infty}^{\infty} [x - E(Q)]^2 \psi(x)^2 dx = \int_{-\infty}^{\infty} \hat{Q}^2 \psi(x)^2 dx.$$

Similarly,

$$\tau^2 = \int_{-\infty}^{\infty} \hat{P}^2 \psi(x)^2 dx.$$

Now,

$$\sigma^2 = \int_{-\infty}^{\infty} \hat{Q}\psi(x) \cdot \hat{Q}\psi(x) dx = \langle \hat{Q}\psi, \hat{Q}\psi \rangle$$

and

$$\tau^2 = \int_{-\infty}^{\infty} \hat{P}\psi(x) \cdot \hat{P}\psi(x) dx = \langle \hat{P}\psi, \hat{P}\psi \rangle.$$

# Simultaneous Pursuit for Certainty

Thus far, we've reduced the product of the variances  $\sigma^2$  and  $\tau^2$  to

$$\sigma^2\tau^2 = \langle \hat{Q}\psi, \hat{Q}\psi \rangle \langle \hat{P}\psi, \hat{P}\psi \rangle.$$

Recall the *dot product* of a vector  $\mathbf{a}$  with itself is  $\mathbf{a} \cdot \mathbf{a} = \|\mathbf{a}\|^2$ . Similarly,

$$\sigma^2\tau^2 = \|\hat{Q}\psi\|^2 \|\hat{P}\psi\|^2.$$

Again, using the dot product for guidance,

$$\|\mathbf{a}\| \|\mathbf{b}\| \geq \|\mathbf{a}\| \|\mathbf{b}\| \cos\theta = |\mathbf{a} \cdot \mathbf{b}|$$

$$\Rightarrow \|\mathbf{a}\|^2 \|\mathbf{b}\|^2 \geq |\mathbf{a} \cdot \mathbf{b}|^2$$

$$\Rightarrow \sigma^2\tau^2 = \|\hat{Q}\psi\|^2 \|\hat{P}\psi\|^2 \geq \left| \langle \hat{Q}\psi, \hat{P}\psi \rangle \right|^2.$$

# Simultaneous Pursuit for Certainty

The inequality  $\sigma^2\tau^2 \geq \left| \langle \hat{Q}\psi, \hat{P}\psi \rangle \right|^2$  still depends on  $\psi$ . Note that

$$\langle \hat{Q}\psi, \hat{P}\psi \rangle = \langle (\hat{P} \circ \hat{Q})\psi, \psi \rangle.$$

Now,  $\sigma^2\tau^2 \geq \left| \langle (\hat{P} \circ \hat{Q})\psi, \psi \rangle \right|^2$ . Let's be clever again!

$$\hat{P} \circ \hat{Q} = \frac{1}{2}(\hat{P} \circ \hat{Q}) + \frac{1}{2}(\hat{P} \circ \hat{Q}) = \frac{1}{2}(\hat{P} \circ \hat{Q} + \hat{Q} \circ \hat{P}) + \frac{1}{2}i.$$

$$\begin{aligned} \Rightarrow \sigma^2\tau^2 &\geq \left| \langle (\hat{P} \circ \hat{Q})\psi, \psi \rangle \right|^2 = \left| \left\langle \left[ \frac{1}{2}(\hat{P} \circ \hat{Q} + \hat{Q} \circ \hat{P}) + \frac{1}{2}i \right] \psi, \psi \right\rangle \right|^2 \\ &= \left| \left\langle \frac{1}{2}(\hat{P} \circ \hat{Q} + \hat{Q} \circ \hat{P})\psi, \psi \right\rangle + i \left( \frac{1}{2} \langle \psi, \psi \rangle \right) \right|^2 \end{aligned}$$

# Simultaneous Pursuit for Certainty

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# Heisenberg Uncertainty Principle

Therefore,  $\sigma^2\tau^2 \geq \frac{1}{2}^2 = \frac{1}{4}$ . Although  $\sigma^2$  and  $\tau^2$  depend on  $\psi$ , the product of their variances is bounded below by  $\frac{1}{4}$ , *independent of  $\psi$* .

This is known as the **Heisenberg Uncertainty Principle**.

<https://www.desmos.com/calculator/txeovzdmb1>

Thank you!